

# MOST LIKELY PATH (MLP)

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*Most likely path* of protons inside a patient – Existing methods and studies

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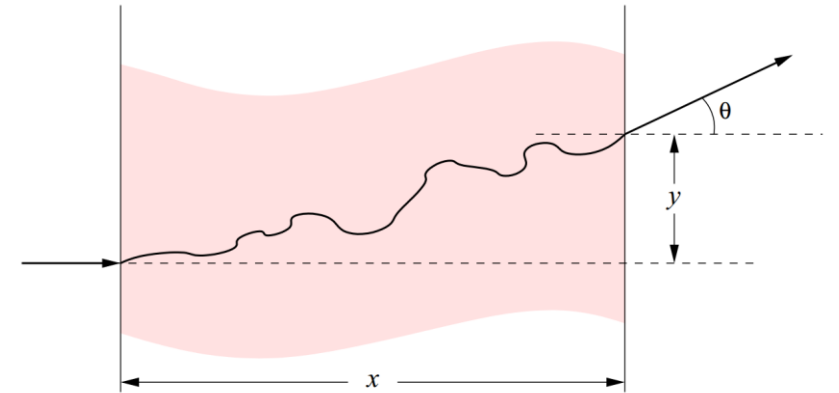
Bergen pCT - Workshop

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# How mlp benefits proton CT

- Protons are affected by multiple Coulomb scattering
- Challenging reconstruction, which voxels are hit?
- In proton CT, individual protons can be distinguished
- Predict the protons most likely path inside the patient using MLP methods
  - Proton path predictions should be accurate enough to help reach the goal of 1 mm spacial granularity and 1% electron density resolution accuracy along the trajectory (Schulte et al 2003).



# Typical proton CT setup, with trackers

- Two trackers in the front of the patient/phantom and two behind
- Phantom is assumed to be homogeneous in current MLP methods

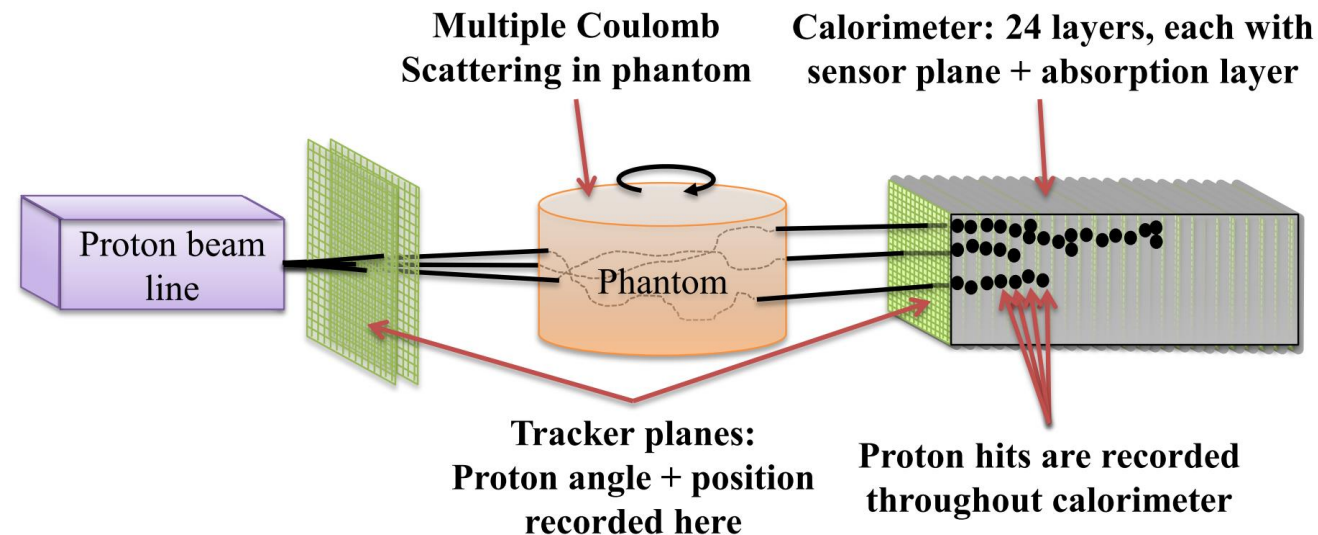


Figure from: H.E.S. Pettersen , 2018, "A Digital Tracking Calorimeter for Proton Computed Tomography"

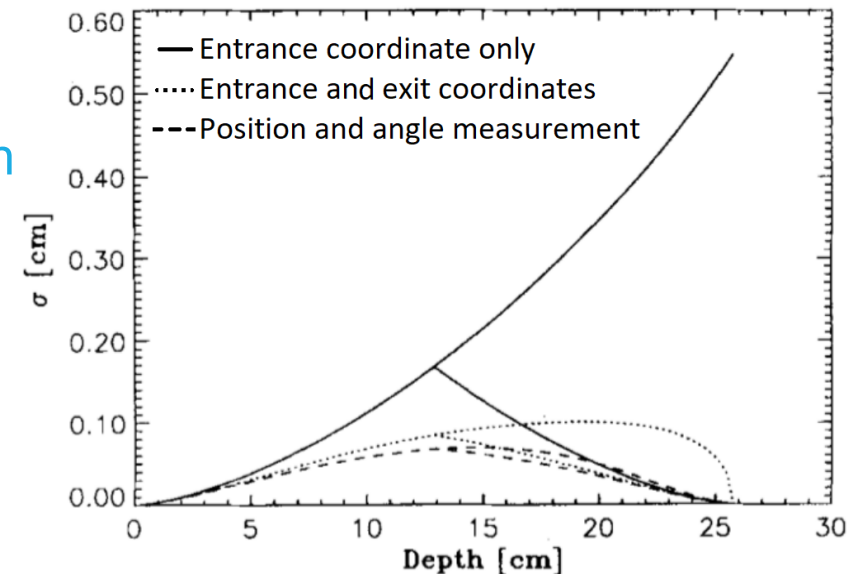
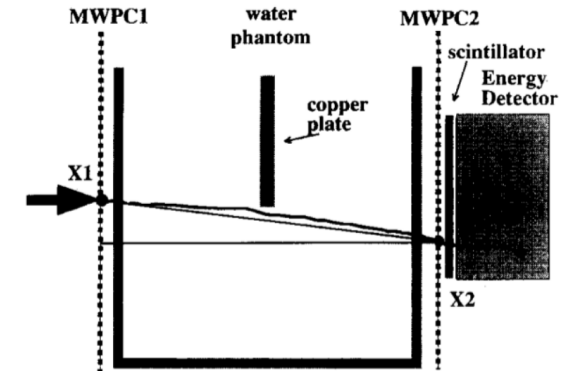
# Multiple Coulomb scattering and spatial resolution in proton radiography

Uwe Schneider and Eros Pedroni

*Department of Radiation Medicine, Paul-Scherrer-Institut, 5232 Villigen-PSI, Switzerland*

(Received 22 June 1993; resubmitted 27 December 1993; accepted for publication 23 June 1994)

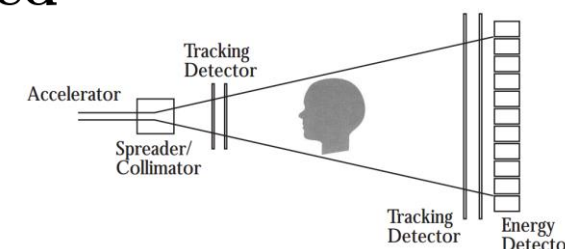
- Earliest results deriving protons internal path between two points
- Analytical formulas account for energy loss in the material
  - Based on generalized Fermi-Eyges theory of scattering
  - Gaussian distribution of scattering angles
  - Derive projected distribution function (mlp)
  - Compared with experimental results
- Calculates spatial resolution of 200 MeV protons in water using varying amount of parameters



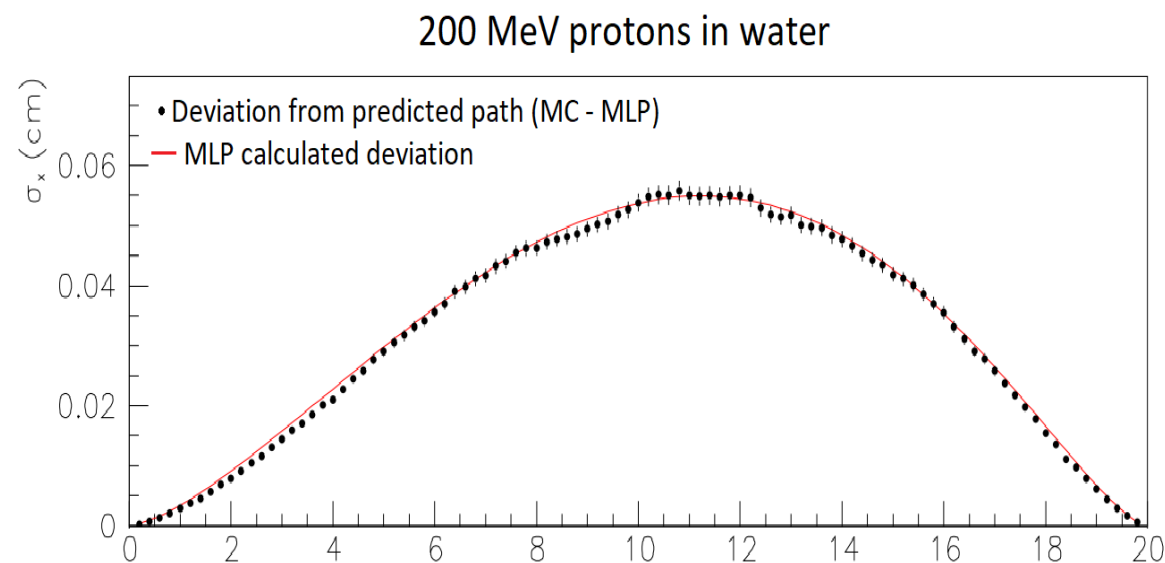
# The Most Likely Path of an Energetic Charged Particle Through a Uniform Medium

D.C. Williams

Santa Cruz Institute for Particle Physics, Santa Cruz, CA 95064, USA



- Calculation of the most likely path with known entrance and exit positions and angles, along with a probability envelope
  - Verified using Monte Carlo simulations (geant4)
- Closely follows the work by Schneider and Pedroni (1994), but simplifies it with a  $\chi^2$  formalism
- MLP predicted path is accurate to  $< 1$  mm
- Observe good agreement between calculation and Monte Carlo simulation

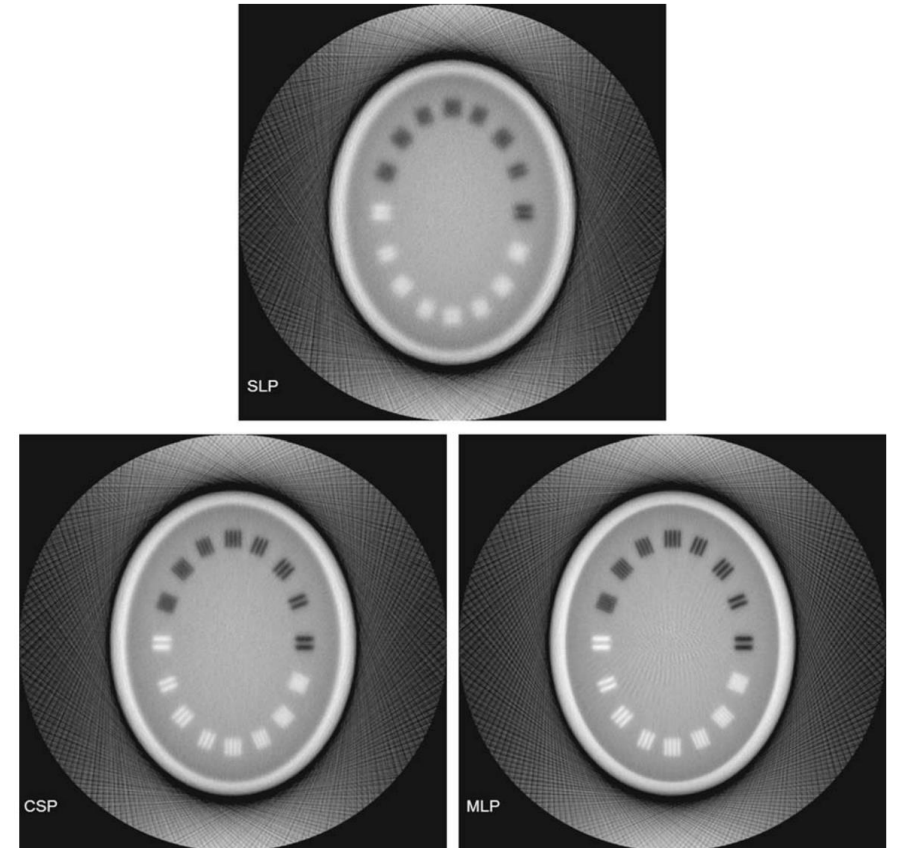
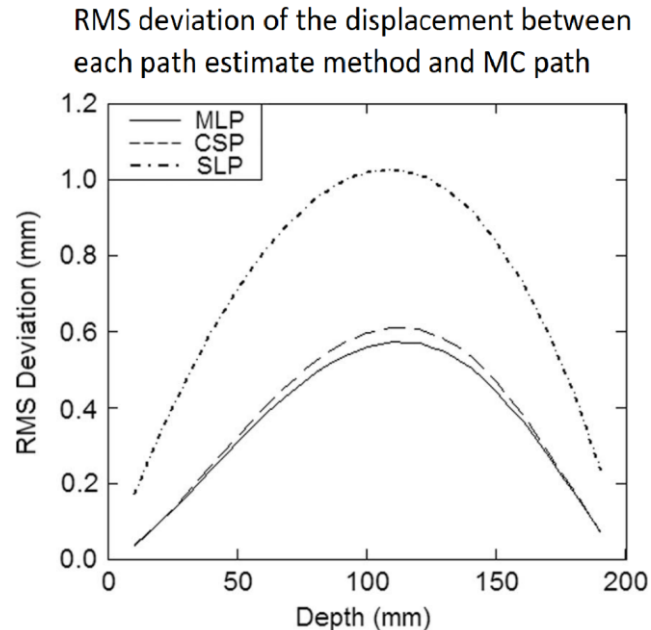


# Reconstruction for proton computed tomography by tracing proton trajectories: A Monte Carlo study

Tianfang Li and Zhengrong Liang<sup>a)</sup>

*Departments of Radiology, Computer Science, and Physics and Astronomy, State University of New York at Stony Brook, Stony Brook, New York 11794*

- Compares three different path-estimation methods used in proton CT
  - Straight Line Path (SLP)
  - Cubic Spline Path (CSP)
  - Most Likely Path (MLP) <- D.C. Williams
- RMS difference between MLP and CSP is no more than 10%



# A maximum likelihood proton path formalism for application in proton computed tomography

R. W. Schulte<sup>a)</sup>

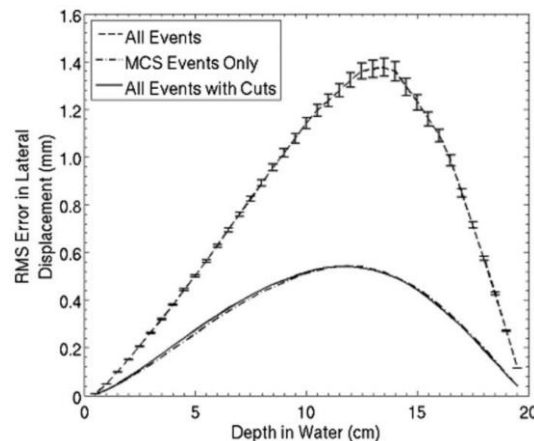
*Department of Radiation Medicine, Loma Linda University Medical Center, Loma Linda, California 92354*

- Matrix based MLP method employing Bayesian statistics
  - Equivalent to MLP formalism by D.C. Williams, but more compact and adaptable
  - Applied to scenarios with incomplete proton track information (D.C. Williams's require information about entrance, exit and angle)
- Able to predict MC tracks of 200 MeV protons in water to within 0.6 mm, using a  $3\sigma$  cut on the relative exit angle

$$y = \begin{pmatrix} t_1 \\ \theta_1 \end{pmatrix} \quad \begin{array}{l} t_1 = \text{lateral coordinate} \\ \theta_1 = \text{angle relative to reference axis} \end{array}$$

$y_d$  = parameter vector at depth  $d$

Bayes' theorem relates the prior and posterior likelihood,  $L$

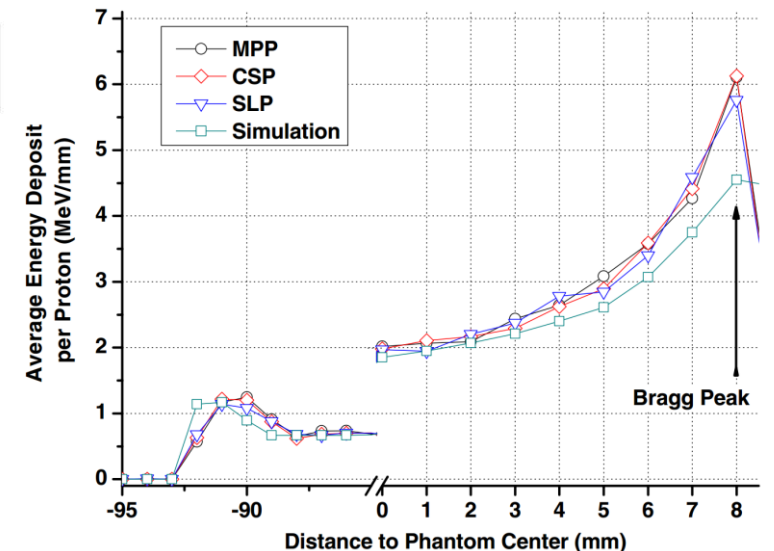
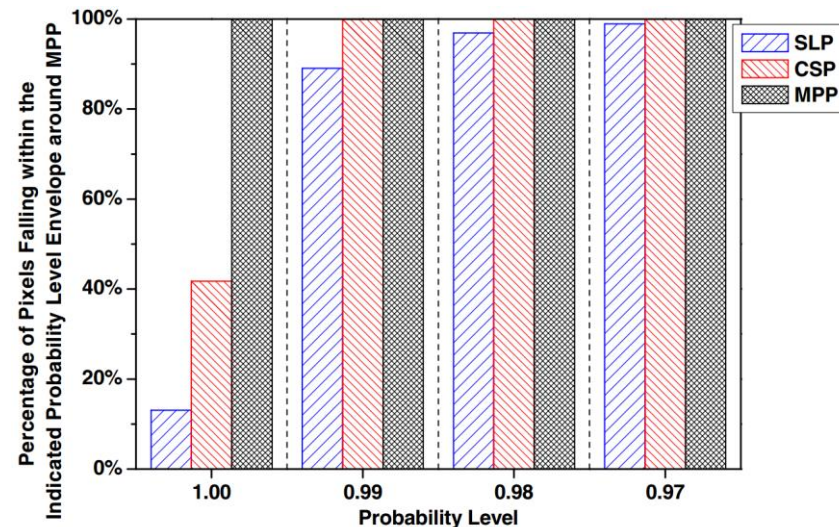
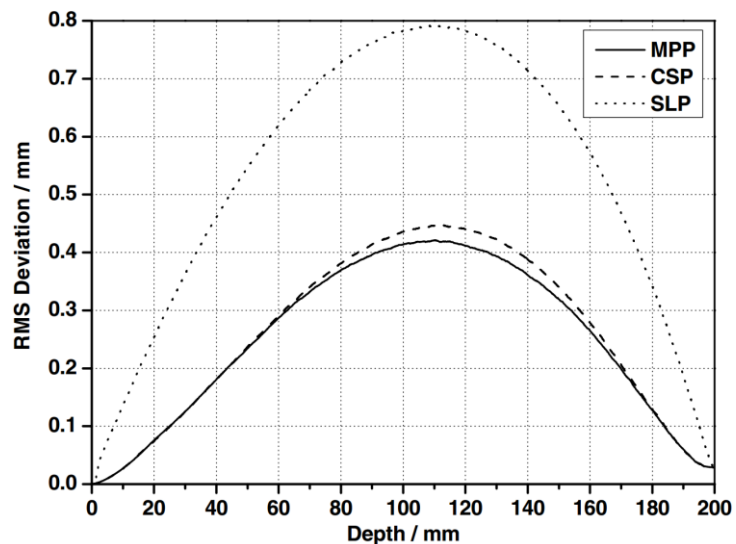
$$L(y_d | \text{exit data}) = L(\text{exit data} | y_d) L(y_d | \text{entry data})$$




# Bragg peak prediction from quantitative proton computed tomography using different path estimates

Dongxu Wang , T Rockwell Mackie and Wolfgang A Tomé

- Compares SLP and CSP performance with MLP and MC
  - Predicting the Bragg peak location
- Employing SLP or CSP may yield lower spatial resolution, but can still accurately predict Bragg peak location

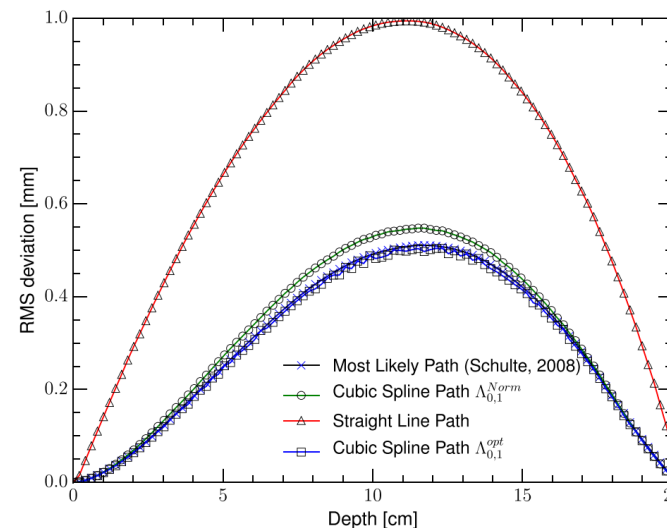
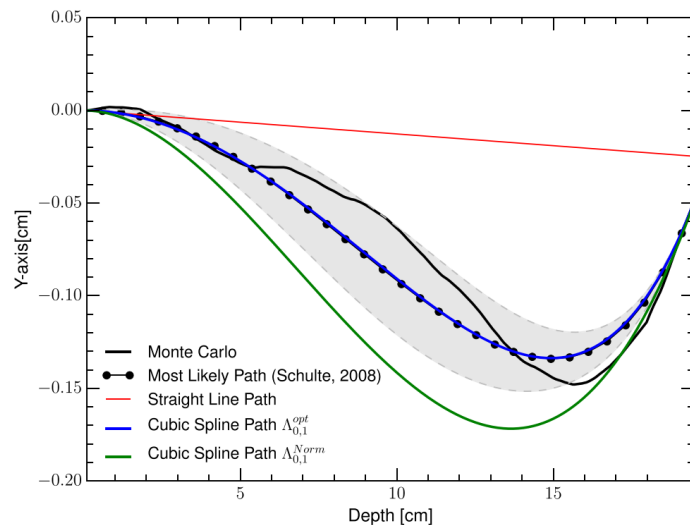


# Developing a phenomenological model of the proton trajectory within a heterogeneous medium required for proton imaging

Charles-Antoine Collins Fekete , Paul Doolan , Marta F Dias , Luc Beaulieu , Joao Seco

- Motivated by the computational burden of MLP, and the reasonably good estimation power of CSP
- Improve the estimation power of CSP by introducing an optimized factor when calculating the direction vector magnitude used in CSP.

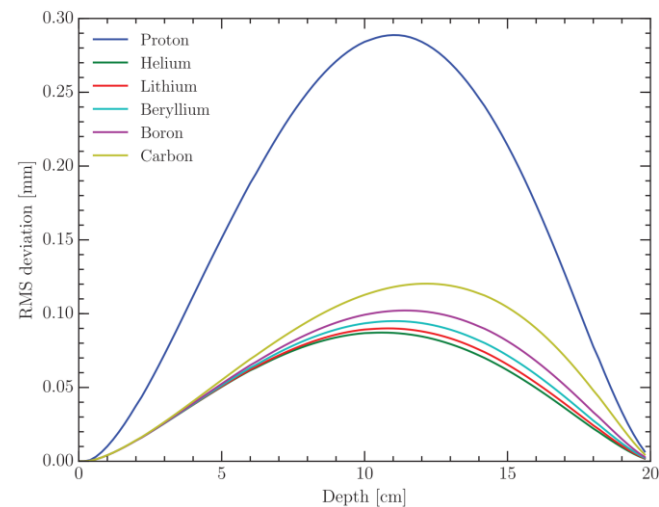
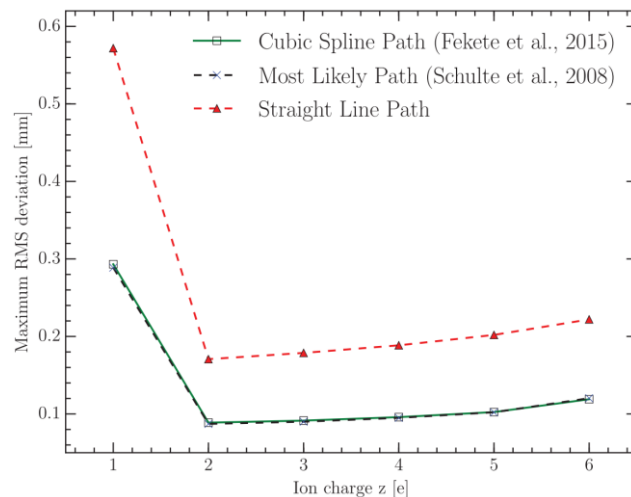
$$\Lambda_{0,1}^{\text{opt}} = A + B(\text{WET}/\text{WEPL})^2$$



# A theoretical framework to predict the most likely ion path in particle imaging

Charles-Antoine Collins-Fekete , Lennart Volz ,  
Stephen K N Portillo , Luc Beaulieu and Joao Seco

- A rigorous Bayesian formalism predicting the MLP of any ion between two points
  - First to extract ions MLP
- Based on the work by Schulte (2008), but more compact
- The optimized CSP is concluded to be an efficient characterization of MLP



# Summary

- All studies apply Gaussian approximation of MCS and use the same scattering theory foundation (Fermi-Eyges theory)
- Only homogeneous materials are considered
  - Scattering in two perpendicular planes are treated as uncorrelated and investigated separately.
- The MLP Bayesian formalism has become more compact (2008-2017)
  - The CSP formalism provides a good and less resource heavy estimation of the proton path
- All methods (except SLP) report a sub-mm deviation from MC

# Going forward – Bergen pCT

- MC simulations
  - Four trackers, two on both sides of a homogeneous water phantom
- Implement CSP method
  - Basic and optimized version
- Implement MLP method
  - Williams,  $\chi^2$  formalism
  - Fekete, Bayesian formalism
- Investigate the effect of removing the two front trackers.
- Inhomogeneous materials(?)
  - Iteratively update the MLP with density information
  - Take advantage of the information found in MCS

